## ADT and Data structures. Local Range ADT

[Review 02.05]
by Marina Barsky

## Example 1: Closest Height

Find 3 people in your class whose height is closest to yours.


## Example 2: Date Ranges

## Find all emails received in a given period

| Inbox |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| FROM | KNOW | T0 | Subject | SENT TIME V |  |
| "lawiki.i2p admin" <J5uF> |  | Bote User <uhod> | hi | Unknown | E |
| anonymous |  | Bote User <uhod> | Sanders 2016 | Aug 30, 2015 3.27 PM | - |
| anonymous |  | Bote User <uhOd> | \|2PCon 2016 | Aug 30, 2015 3:25 PM | - |
| Anon Developer <gvbM> |  | Bote User <uhod> | Re: Bote changess | Aug 30, 2015 2:54 PM | - |
| I2P User <uUUx> |  | Bote User <uhod> | Hello World! | Aug 30, 2015 2:51 PM | - |

## Example 3: Partial Matching

Find all words that start with some given prefix


## Abstract Data Type: Local Range

## Specification

A Local Range ADT stores a number of elements each with a key and supports the following operations:
$\rightarrow \quad$ RangeSearch(lo, hi): returns all elements with keys between 10 and $h i$

Reduces to find( $x$ ) if $x=l o=h i$
$\rightarrow \quad$ NearestNeighbors $(x, k)$ : returns $k$ elements with keys closest to $x$

$$
\text { when } k=1 \text { : }
$$

you want successor(x)
or you want predecessor(x)

## Sorted Keys



The best idea for these queries is to store the keys in a sorted order

## Dynamic Data Structure

> Store keys in sorted order
> Also want to be able to add/remove keys efficiently:
$\operatorname{Insert}(X)$ : Adds an element with key $X$
Delete ( $x$ ): Removes the element with key $x$

## Data Structures for Range ADT

\section*{| 1 | 4 | 6 | 7 | 10 | 13 | 15 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |}

Let's try known data structures:
> Unsorted Array
> Sorted Array
> Sorted Linked List
> Hash table

## Unsorted Array

$\rightarrow$ Range Search:<br>$O(n) \times$<br>$\rightarrow \quad$ Nearest Neighbors:<br>$O(n) \times$<br>$\rightarrow$ Insert:<br>$\rightarrow$ Delete:<br>$O(1) \mathrm{V}$<br>$O(1) \vee$

delete (10)


## Sorted Array

$\rightarrow \quad$ Range Search: $\quad O(\log (n)) \vee$<br>$\rightarrow \quad$ Nearest Neighbors: $\quad O(\log (n)) \vee$<br>$\rightarrow$ Insert: $\quad O(n) \times$<br>$\rightarrow$ Delete: $\quad O(n) \times$

## delete (6)



## Sorted Linked List

$\rightarrow$ Range Search:<br>$O(n) \times$<br>$\rightarrow \quad$ Nearest Neighbors:<br>$O(n) \times$<br>$\rightarrow$ Insert:<br>$\rightarrow$ Delete:<br>$O(n) \times$<br>$O(n) \times$

delete (6)


## Hash Table



## Nothing works

> We want efficient data structure for Local Range ADT
> None of the existing data structures work
> Sorted arrays are good for search but not for update

## We need something new

## Binary Search



## Record search questions



## We get a tree



## Binary Search Tree



## Tree levels and node depth



Depth: distance from the root how many edges to go from the root to a

## Node height



Height: distance from the node to the bottom: how many edges to go to the furthest leaf

## Tree - recursive data structure

- Main element of the tree: node
- Each node contains data and an array of
- links to the child nodes
node_addr

typedef struct node \{
int data;
struct node ** children;
[struct node * parent;]
class TreeNode:

$$
\begin{aligned}
& \text { def } \text { _init__(self, data) : } \\
& \text { self.data = data } \\
& \text { self.children = [] } \\
& {[\text { self.parent }=\text { None }] }
\end{aligned}
$$

\} TreeNode;

## Tree is defined by a single node

Tree is either

- $\quad$ Null (empty tree)
- Root node which contains data and links to child nodes



## Binary tree: at most 2 children


typedef struct node \{
int data;
struct node * left;
struct node * right;
[struct node * parent;]
class TreeNode: def __init__(self, data): self.data = data self.left = None self.right = None [self.parent = None]
\} TreeNode;

## Recursive algorithms are common

## Algorithm Height (node)

if node is Null :
return 0
if node.left is Null and node.right is Null:
return 0
return $1+\operatorname{Max}(H e i g h t(n o d e . l e f t), H e i g h t(n o d e . r i g h t))$

## Algorithm Size (tree)

if tree is Null
return 0
return $1+\operatorname{Size}($ tree.left $)+\operatorname{Size}($ tree.right)

## Tree traversals

How do we list all the nodes in the tree?

Two types of traversals:

* Depth-first: we completely traverse one sub-tree before exploring a sibling sub-tree
* Breadth-first: We traverse all nodes at one level before progressing to the next level


## Depth-first tree traversals

\author{

- In-order <br> - Pre-order <br> > Post-order
}


## Depth-first: in-order

## Algorithm InOrderTraversal(tree)

if tree = Null :
return
InOrderTraversal(tree.left)
print (tree.key)
InOrderTraversal(tree.right)


## In-order



ABCDEFG

## In-order


me, node D
A B C D E F G
left subtree of $D$
right subtree of D

## Depth-first: pre-order

## Algorithm PreOrderTraversal(tree)

if tree is null:

return

print (tree.key)
PreOrderTraversal(tree.left)
PreOrderTraversal(tree.right)
me first
me - left -right


## Pre-order



D B ACFEG

## Pre-order


me, node D
D

BAC
left subtree of D

F E G
right subtree of $D$

## Depth-first: postorder

## Algorithm PostOrderTraversal(tree)

if tree is null: return
PostOrderTraversal(tree.left)
PostOrderTraversal(tree.right)
print(tree.key)

children first<br>left-right-me



## Post-order



## ACBEGFD

## Post-order


me, node D

## ACB

left subtree of $D$

## E G F

D
right subtree of $D$

## Breadth first



Level traversal:
D
B F
ACEG

## Algorithm BreadthFirstTraversal(tree)

if tree is null: return

Queue $q$
q.Enqueue(tree)
while not q.Empty() :
node $\leftarrow q$.Dequeue()
Print(node)
if node.left!= null:
q.Enqueue(node.left)
if node.right!= null:
q.Enqueue(node.right)

# Breadth first: level traversal 



Queue: D
Output:

# Breadth first: level traversal 



Queue:
Output: D

# Breadth first: level traversal 



Queue: B F
Output: D

# Breadth first: level traversal 



Queue: B F
Output: D

# Breadth first: level traversal 



Queue: F
Output: D B

# Breadth first: level traversal 



Queue: F A C
Output: D B

# Breadth first: level traversal 



Queue: FA C
Output: D B

# Breadth first: level traversal 



Queue: A C
Output: D B F

## Breadth first: level traversal



Queue: A C E G
Output: D B F

## Breadth first: level traversal



Queue: A CEG
Output: D B F

# Breadth first: level traversal 



Queue: C E G
Output: D B F $\underline{A}$

## Breadth first: level traversal



Queue: C E G
Output: D B F A

# Breadth first: level traversal 



Queue: E G
Output: D B F A C

# Breadth first: level traversal 



Queue: E G
Output: D B F A C

## Breadth first: level traversal



Queue: G
Output: D B FACE

## Breadth first: level traversal



Queue: $\underline{G}$
Output: D B F A C E

## Breadth first: level traversal



Queue: empty
Output: D B FACE $\underline{G}$

## Tree-traversal Puzzle 1



Guess the word: in-order traversal

## Tree-traversal Puzzle 2



Guess the word: pre-order traversal

## Tree-traversal Puzzle 3



Guess the word: post-order traversal

## Tree-traversal Puzzle 4



Guess the word: breadth-first traversal

