

Binary Search Trees

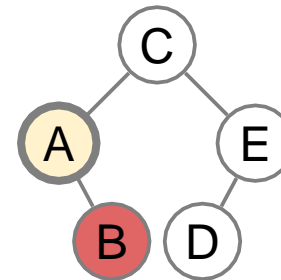
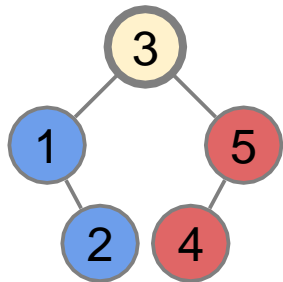
Lecture 02.11

by Marina Barsky

Definition

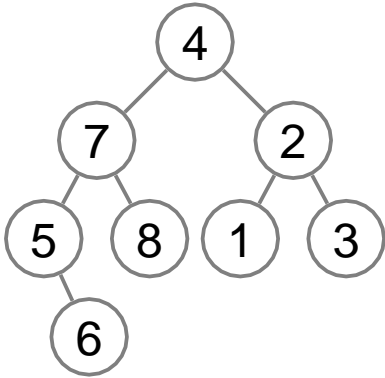
Binary search tree is a binary tree with the following property:

for each node with key x , all the nodes in its **left subtree** have keys **smaller than x** , and all the keys in its **right subtree** are **greater or equal* to x** .

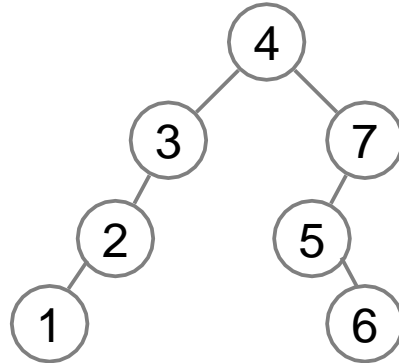


*To simplify the discussion we will assume that all keys are unique, so the keys in the right subtree are strictly greater than x

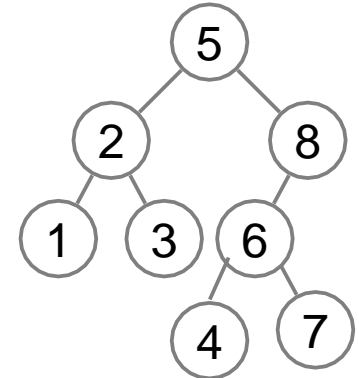
Which one is a Binary Search Tree?



A

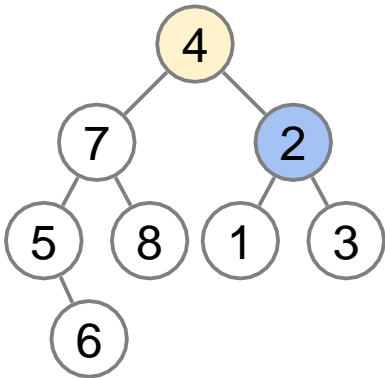


B

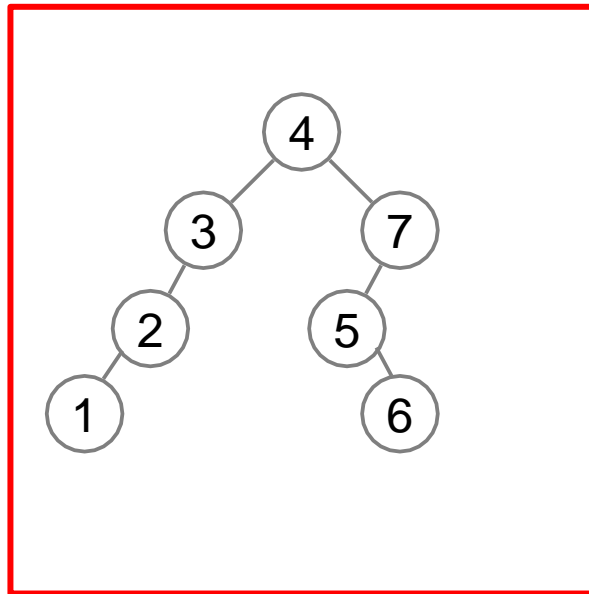


C

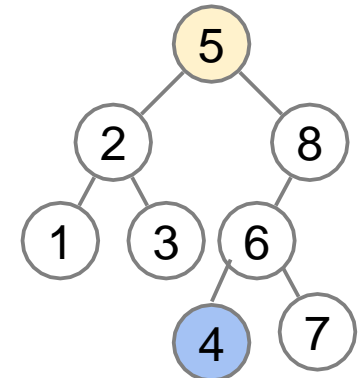
Which one is a Binary Search Tree?



A



B



C

BST Node

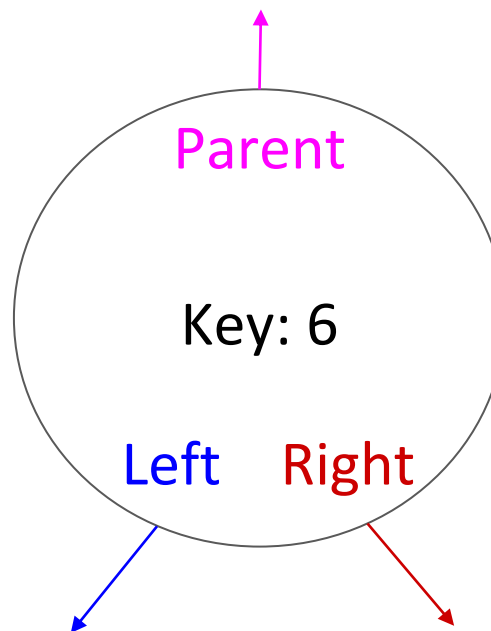
BST Node:

Key

Left

Right

Optional: Parent



BST: read operations

- **Find (k)**: returns tree node with key k
- **Successor (k)**: finds and returns the node in the tree with the smallest key among all keys greater than k - i.e. finds the node with the next to k key in the list of sorted keys
- **Predecessor (k)**: same as successor, but from the left of k - finds and returns the node with the key immediately preceding k in the sorted list of all keys
- **Range (lo , hi)**: returns the list of all tree nodes with keys between lo and hi (inclusive)

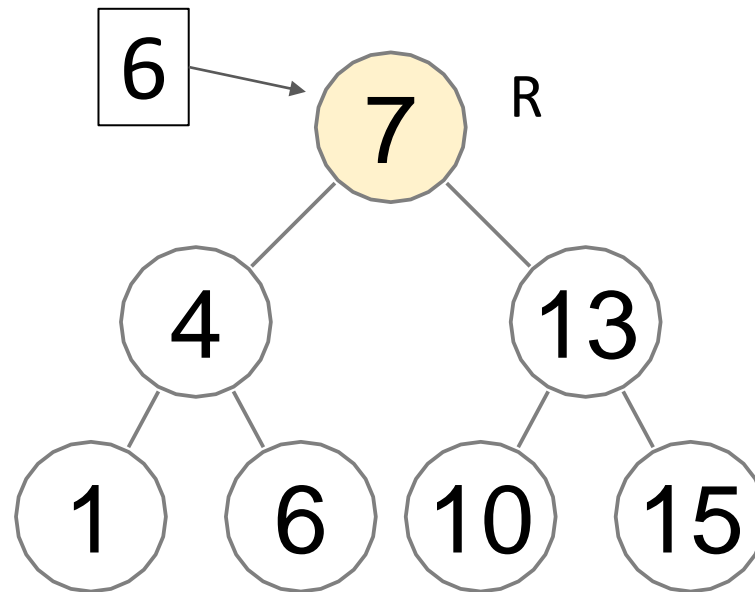
All these operations do not modify the tree

Operation *Find*

Input: Key k , Root R of BST

Output: The node with key k

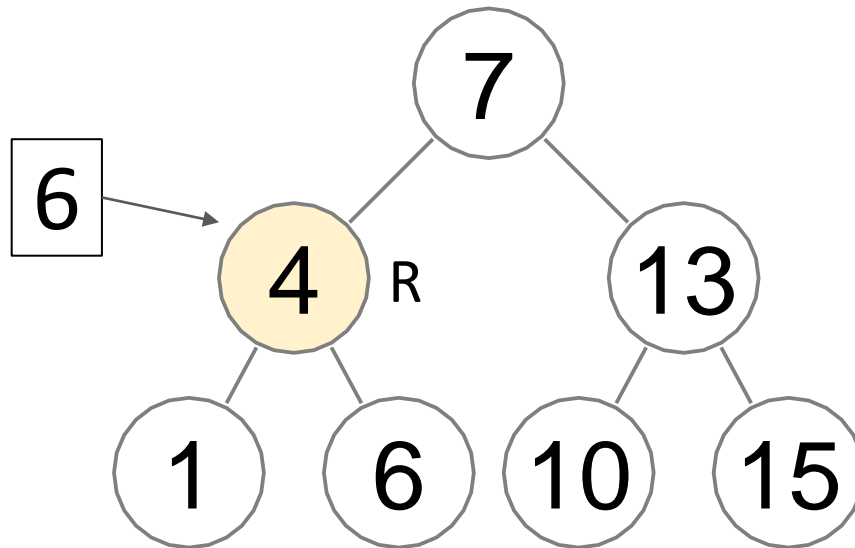
Example: find (6, root R)



$6 < 7$

Root becomes left child of 7

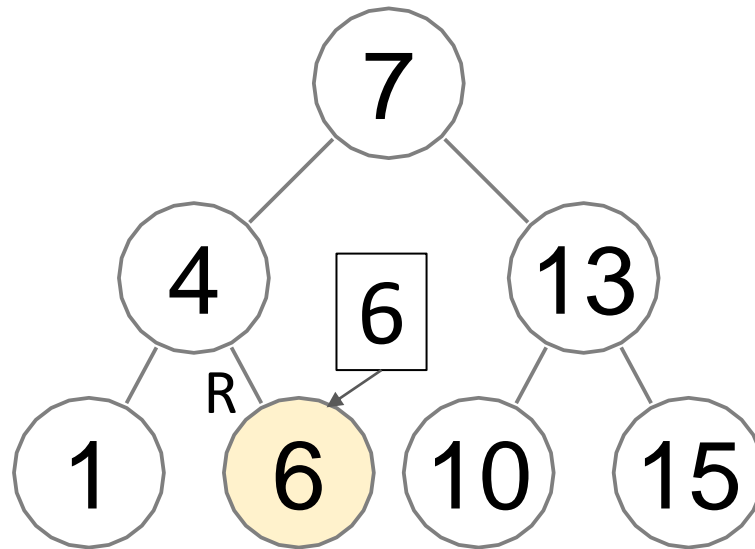
Example: find (6, BST root R)



$6 > 4$

Root becomes right child of 4

Example: find (6, BST root R)



6 = 6

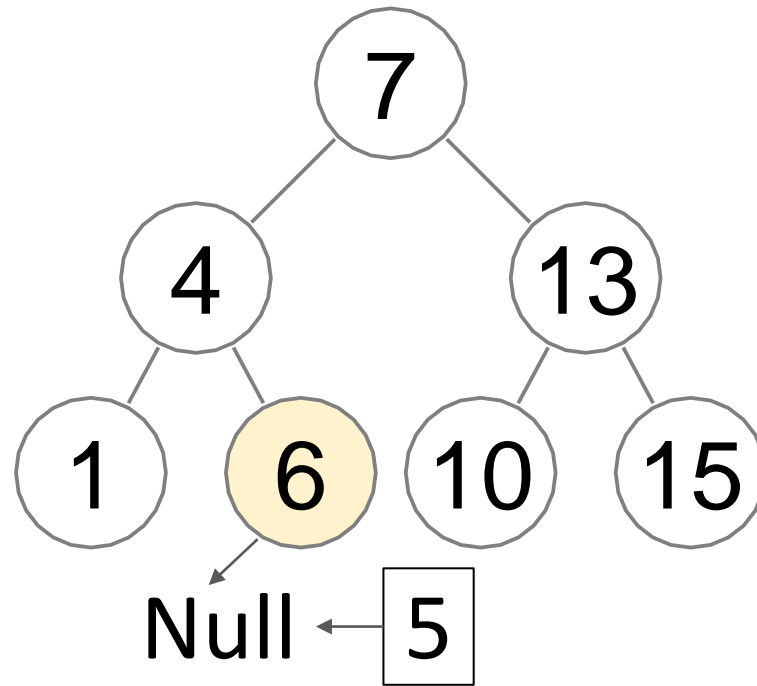
Return node 6

Algorithm *Find* (k, R)

```
if  $R.Key = k$ :    return  $R$ 
if  $R.Key > k$ :
    return Find( $k, R.Left$ )
else if  $R.Key < k$ :
    return Find( $k, R.Right$ )
```

Recursive algorithms are common
But all these algorithms can be
implemented without recursion

Example: find (5, R)



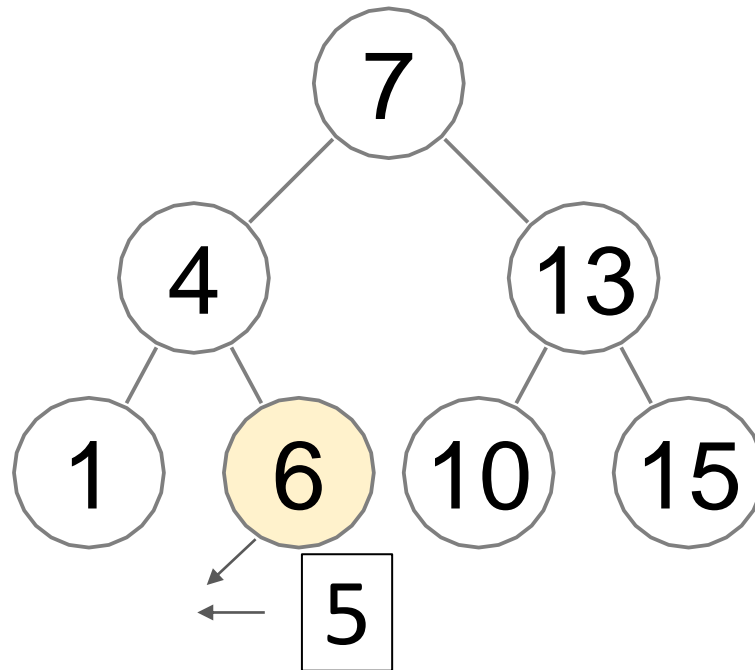
Missing key: return Null

Updated for the case of missing key

Algorithm *Find* (k, R)

```
if  $R$  is Null or  $R.Key = k$ :  
    return  $R$   
if  $R.Key > k$ :  
    return Find( $k, R.Left$ )  
else if  $R.Key < k$ :  
    return Find( $k, R.Right$ )
```

Missing key: find(5, R)



Note: If you stop before reaching null pointer, you find the place in the tree where k would fit.

Given a node N in a Binary Search Tree
- find nodes with adjacent keys

Operation *Successor*

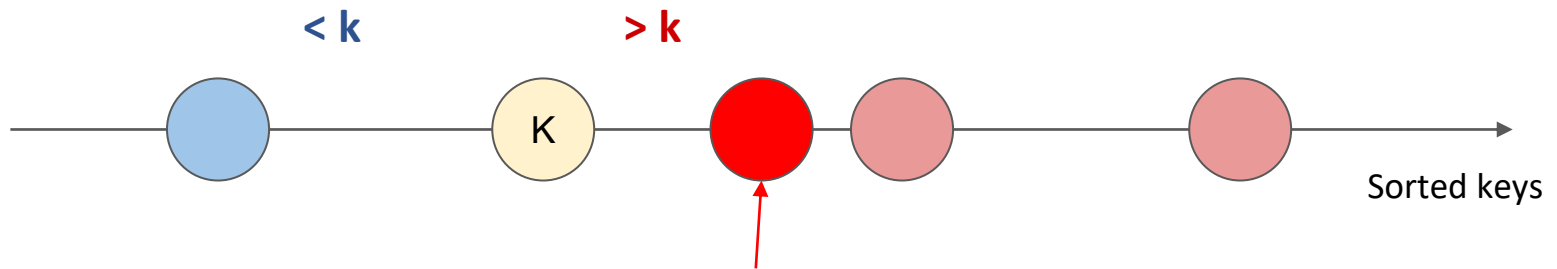
Input: key k

Output: The node in the tree with the next larger key.

Operation *Predecessor*

Input: key k

Output: The node in the tree with the next smaller key.



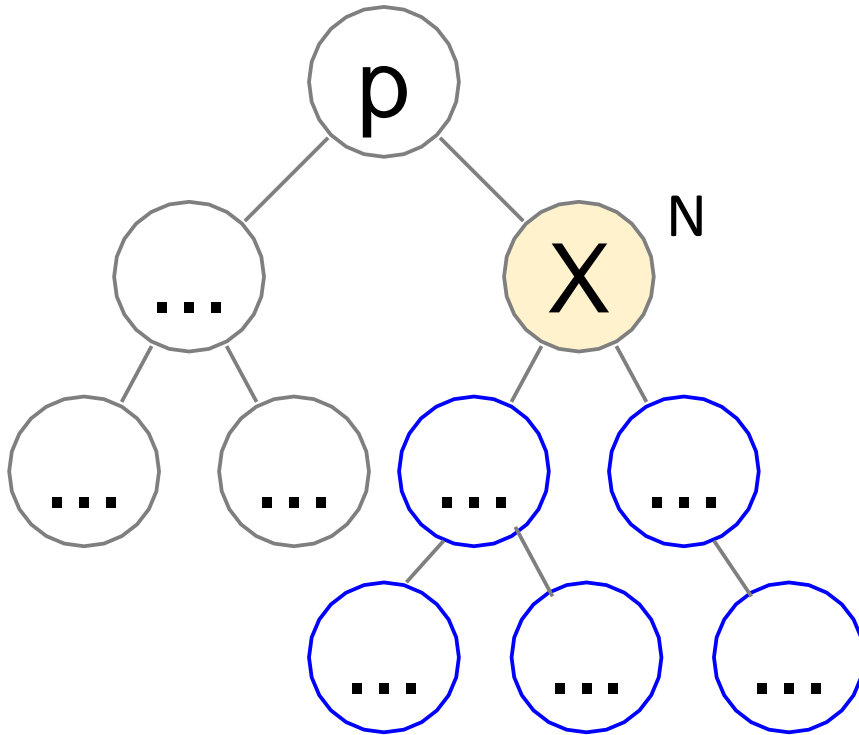
Operation *Successor*

Input: key k

Output: The node in the tree with the next larger key.

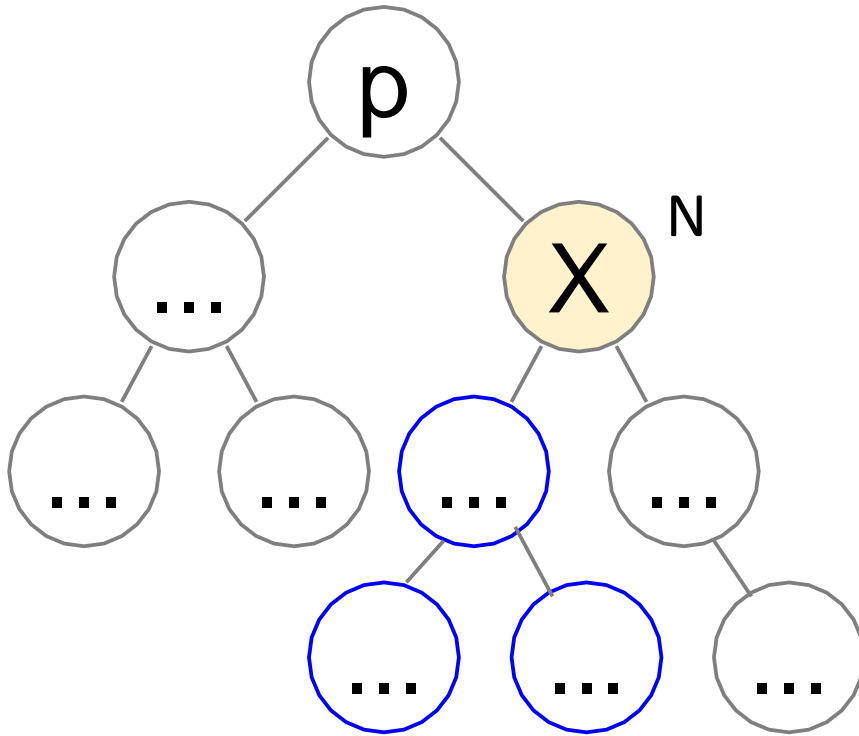
- We want to find the node with the key which is closest to k from above
- We would need a sub-operation *get_min* to solve this problem

Sub-operation: *get_min* (node N)



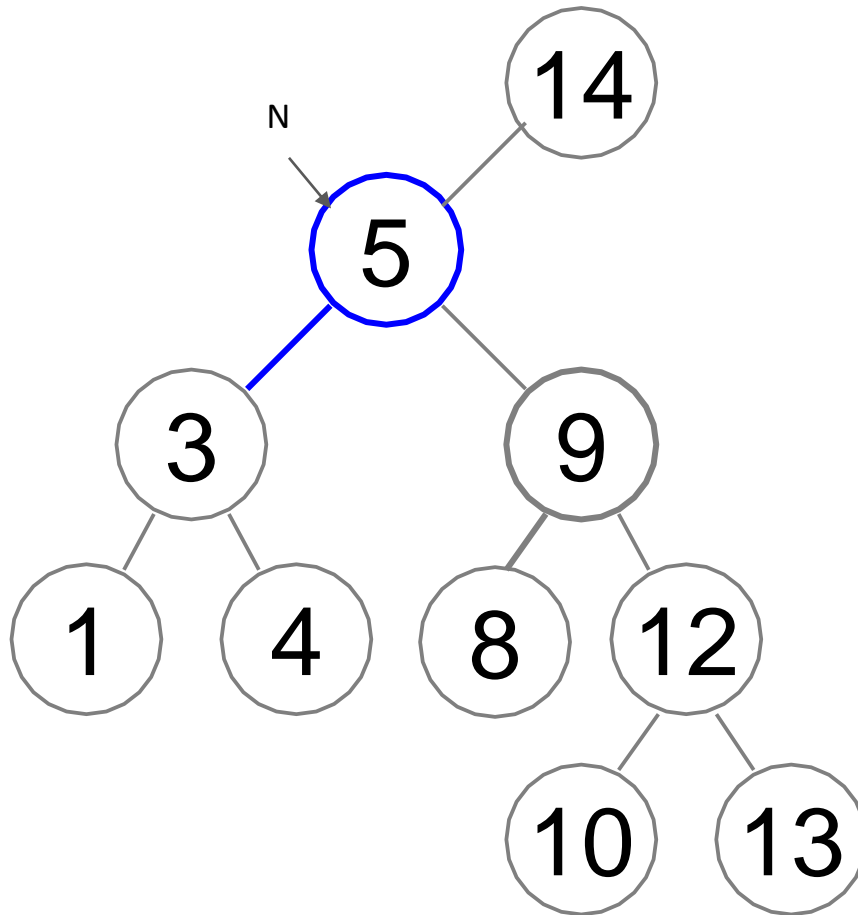
- We want to find min key in a subtree rooted at N

Sub-operation: *get_min* (node N)



- We want to find min key in a subtree rooted at N
- Among all descendants of N the only keys that are $< X$ are in the left subtree of N

Example: *get_min* (N)

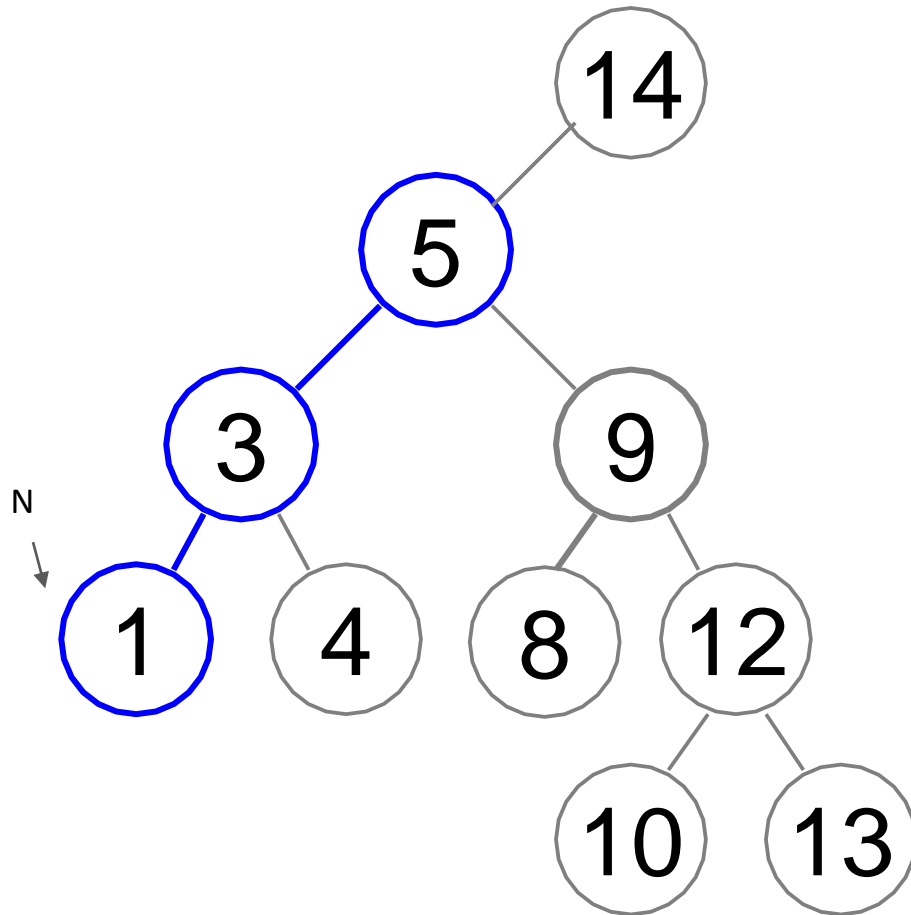


→ Does node N have left child?

Yes → there is a key smaller than 5

→ Set N to be the left child and ask the same question

Example: *get_min* (N)



→ Does node N have left child?
No → there is no key smaller than N

Follow the leftmost path in the tree - until no more left child

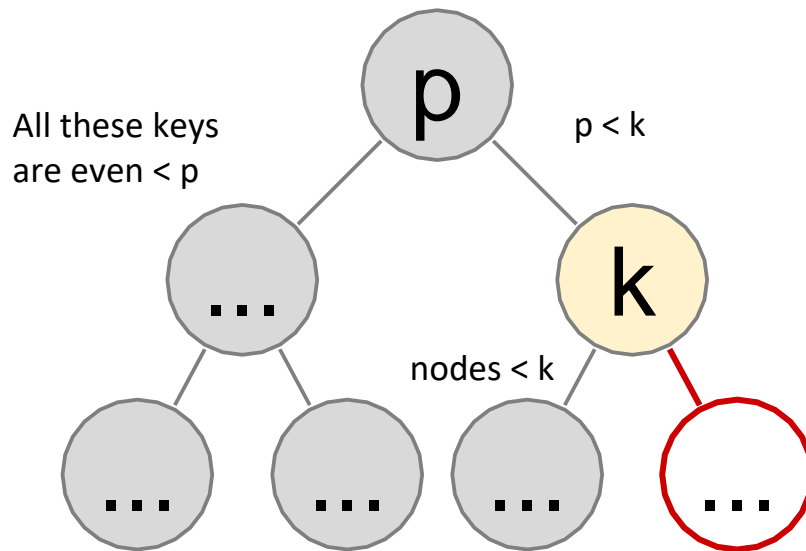
Algorithm *Get_min* (N)

```
if N.Left = null:  
    return N  
else:  
    return Get_min (N.Left)
```

Successor (k)

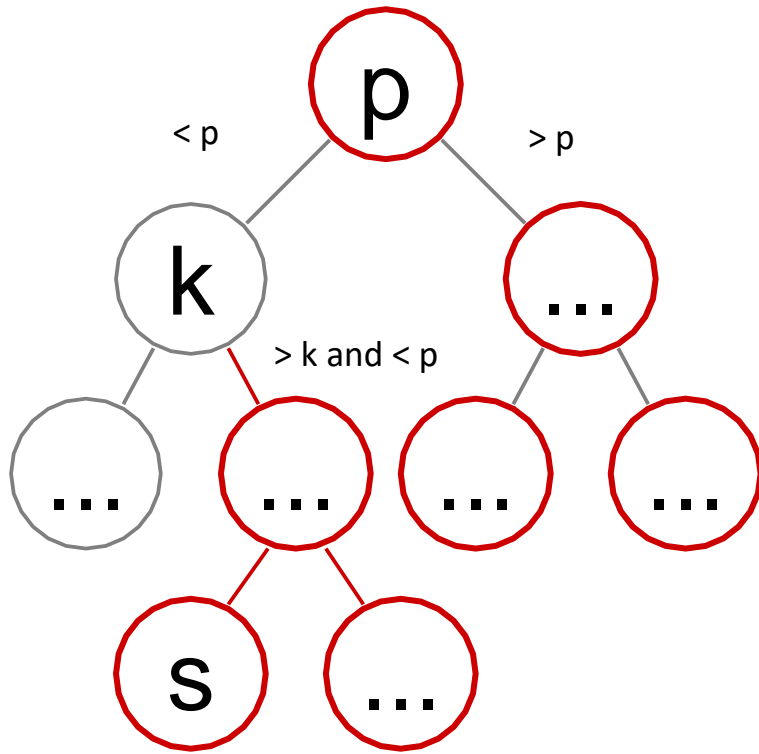
First, find node N with key k

Case 1: N has right child



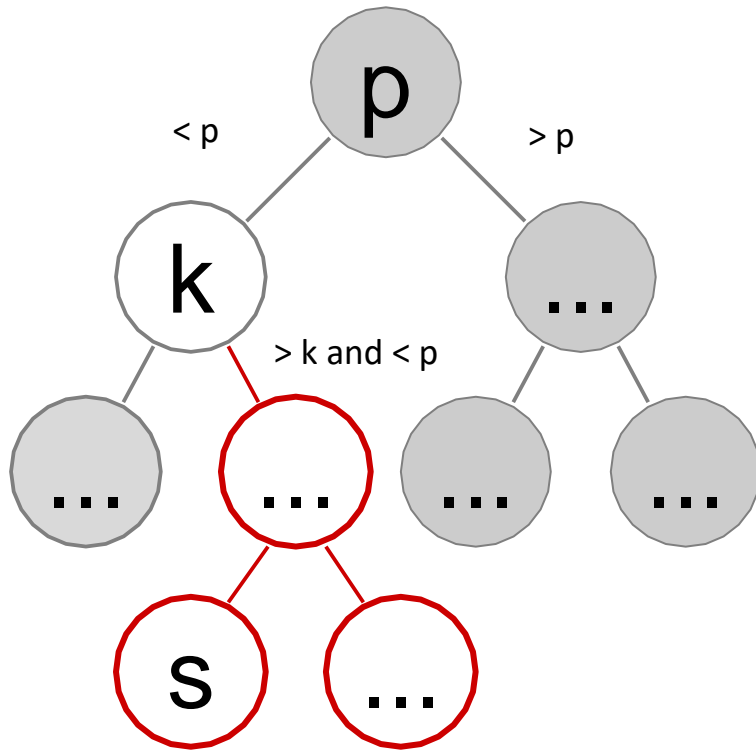
➤ In this situation all keys $> k$ are in the right subtree of N

Case 1: Node N has the right child, but also has a parent with $p > k$



- In this situation there are also keys $> k$ in the parent of N and in the right subtree of the parent
- However we are looking for the **smallest** among these keys
- The min among all keys $> k$ is again in the right subtree of N - because the keys in this subtree are precisely between k and p

Case 1: Node N has the right child, but also has a parent with $p > k$

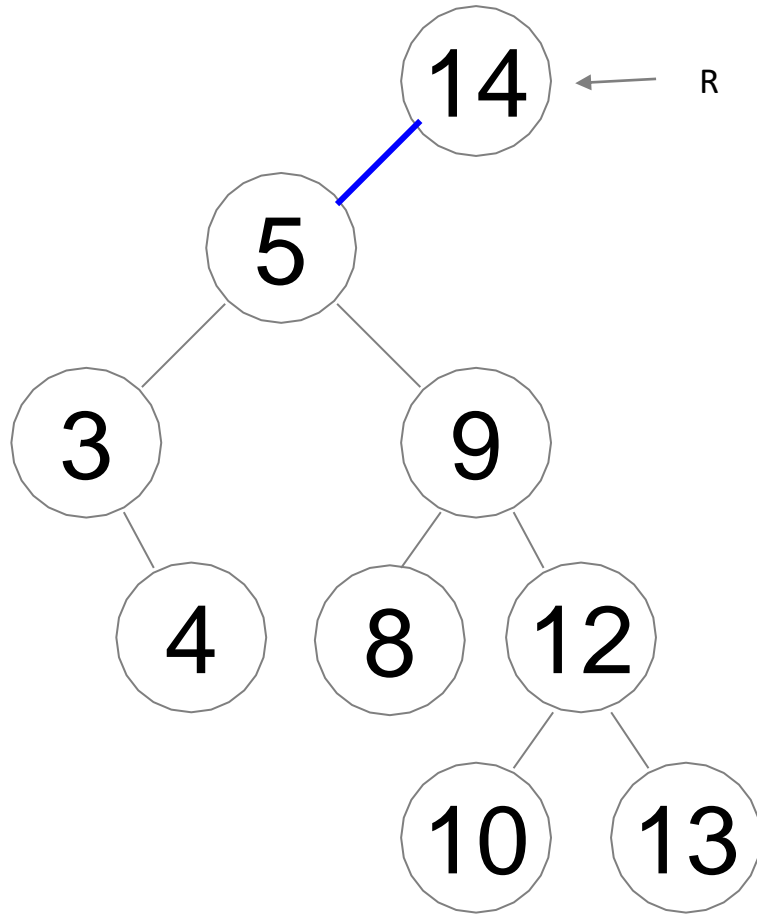


- The goal then becomes to find the smallest among all the keys in the right subtree of N
- Use *get_min* (N .right)

Algorithm *Successor* (k, R)

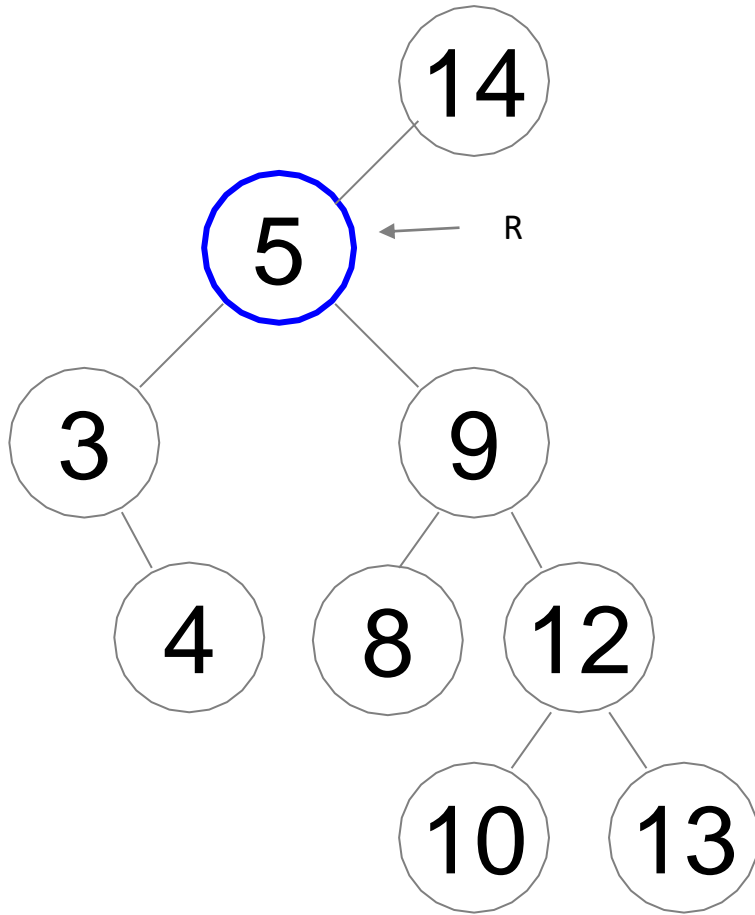
```
if  $R.Key = k$  : # found  $N$ 
    if  $R.Right \neq \text{null}$ :
        return Get_min ( $R.Right$ )
    ...
if  $k < R.Key$ : # continue searching for  $N$ 
    return Successor ( $k, R.Left$ )
    ...
if  $k > R.Key$  : # continue searching for  $N$ 
    return Successor ( $k, R.Right$ )
    ...
```

Example: successor (5, R)



→ Follow the left subtree:
 $5 < 14$

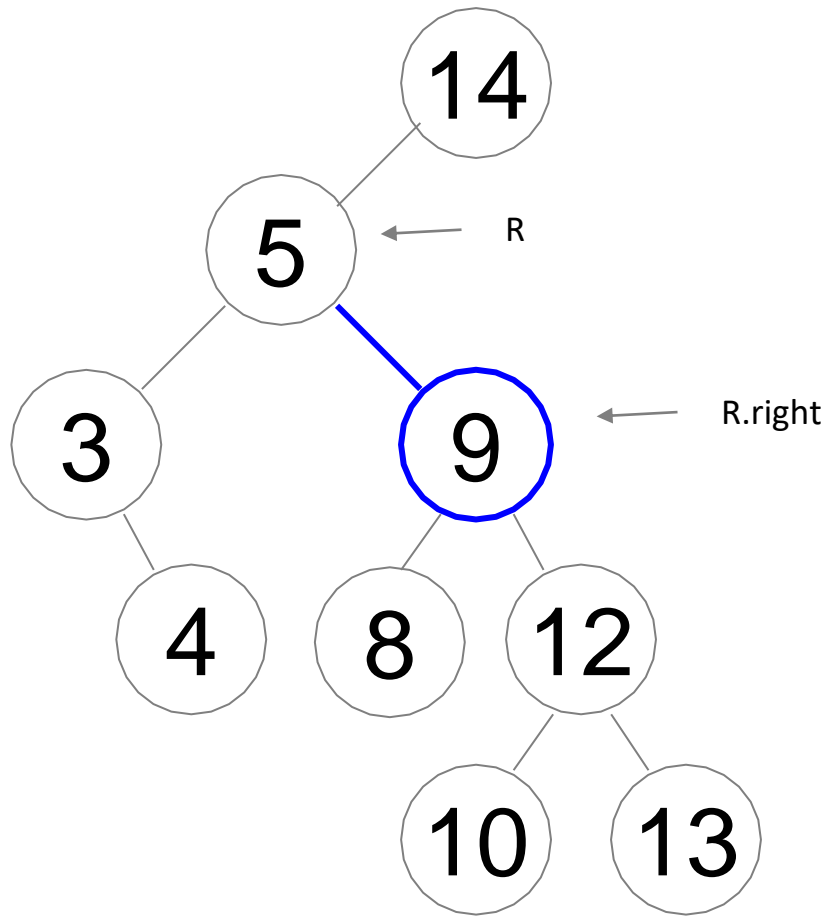
Example: successor (5, R)



→ Follow the left subtree:
 $5 < 14$

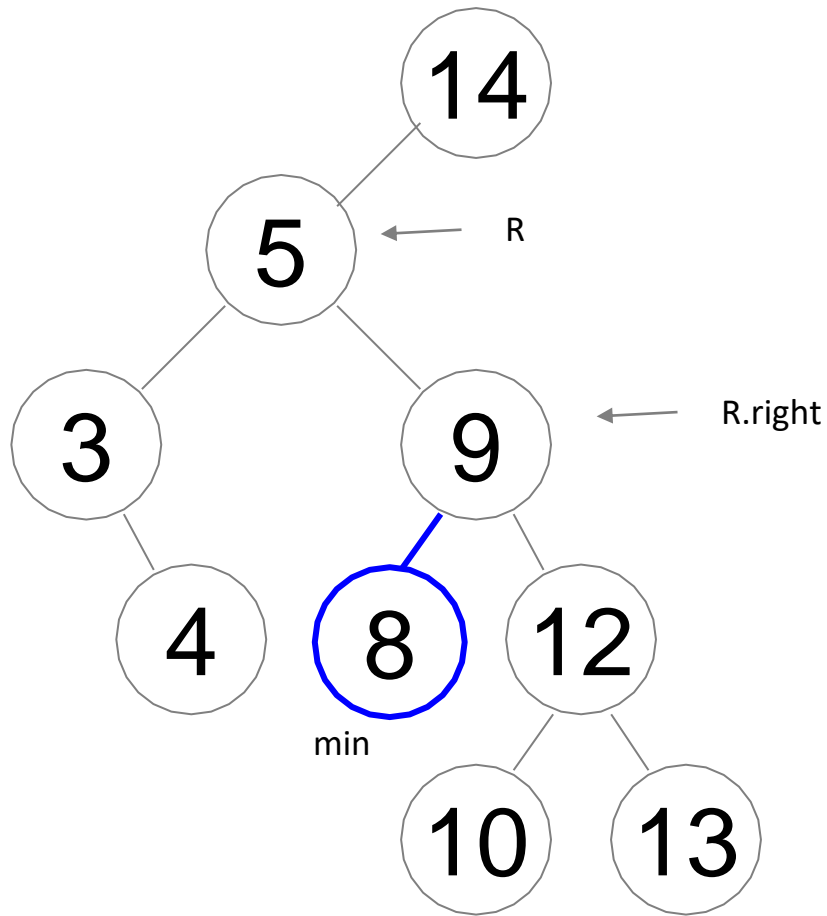
→ Found 5

Example: successor (5, R)



- Follow the left subtree:
 $5 < 14$
- Found 5
- N has right child

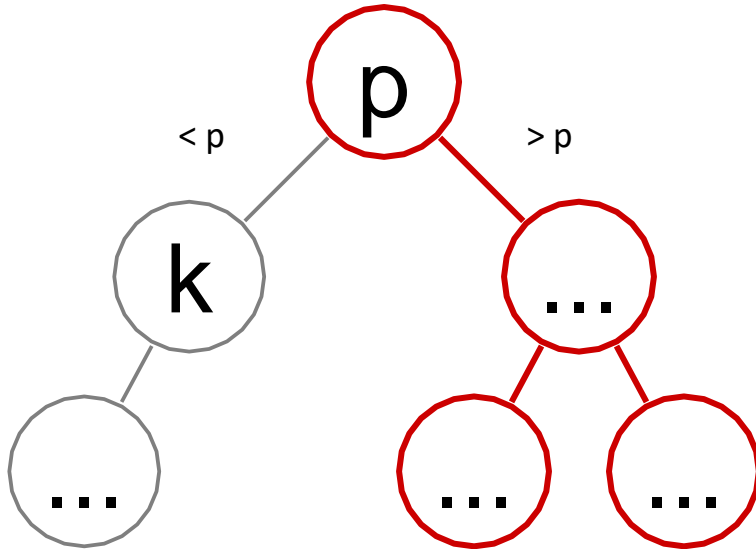
Example: successor (5, R)



- Follow the left subtree:
 $5 < 14$
- Found 5
- N has right child
- *Min* in the subtree rooted at 9 is the successor of 5

successor (5, R) → 8

Case 2: Node N with key k does not have the right child



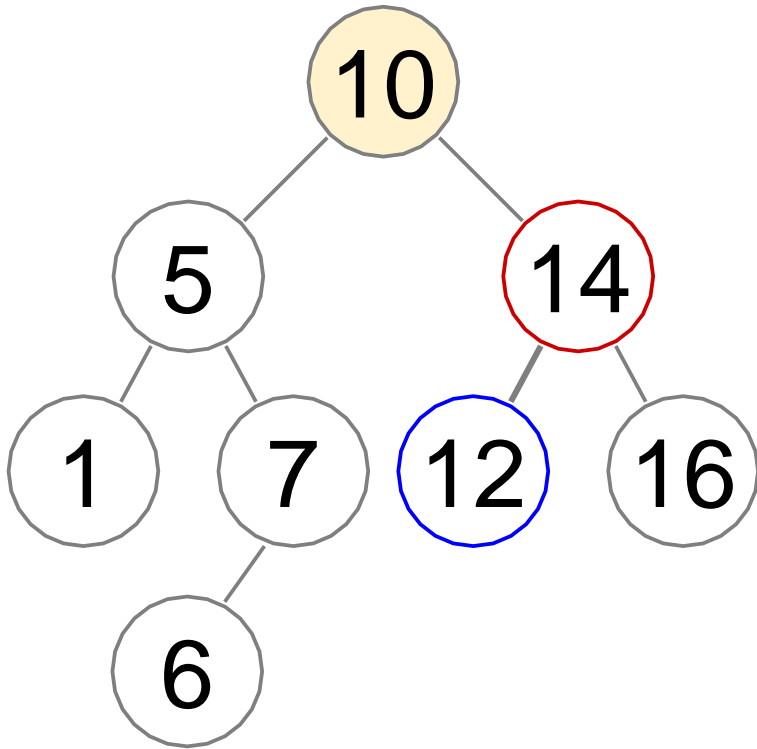
- In this case the successor of N is among N 's ancestors
- Namely the last time we took the turn to left subtree - the key at the root of this subtree is the successor of N
- If we do not have a parent field in our Node, then we cannot recover this parent
- Instead, we will keep track of the last parent when we took the left turn in the search for N

Algorithm *Successor* (k, R, S)

```
if  $R.Key = k$  : # found N
    if  $R.Right \neq \text{null}$ :
        return Get_min ( $R.Right$ )
    else:
        return  $S$ 
if  $k < R.Key$  : # left turn
     $S \leftarrow R$  # remember the parent
    return Successor ( $k, R.Left, S$ )
if  $k > R.Key$ :
    return Successor ( $k, R.Right, S$ )
```

You start this algorithm with $R = \text{root of BST}$
and S (successor) set to null

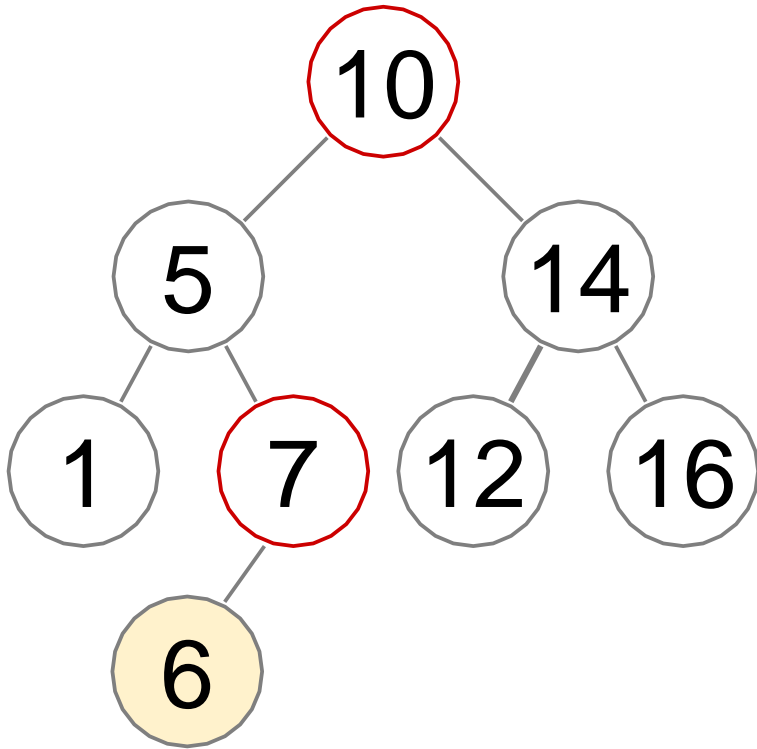
Example: *Successor* (10, R)



→ 10 has right subtree

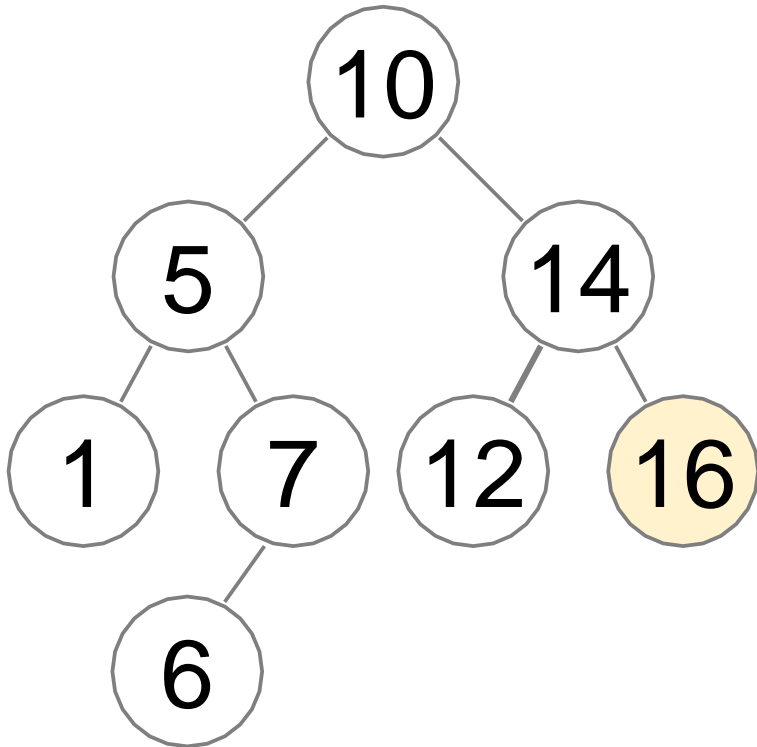
→ Successor is the min in
this right subtree:
Successor (10) → 12

Example: *Successor* (6, R)



- While searching for 6: we update a possible candidate for successor (first 10, then 7) - because we do not know if N will have a right subtree or not
- 6 does not have the right subtree
- Successor is the last ancestor of 6 when we moved into the left subtree:
Successor (6) → 7

Example: *Successor* (16, R)



- While searching for 16: we never took the left turn
 - 16 does not have the right subtree
 - 16 also does not have a successor - it is the largest key in the tree
- Successor* (16) → null

Now that we know how to find a successor,
we can solve the range query

Operation *Range*

Input: Numbers x , y , root R

Output: A list of nodes with keys between x and y

Algorithm RangeSearch (x , y , R)

$L \leftarrow$ empty list

$N \leftarrow \mathit{Find}(x, R)$

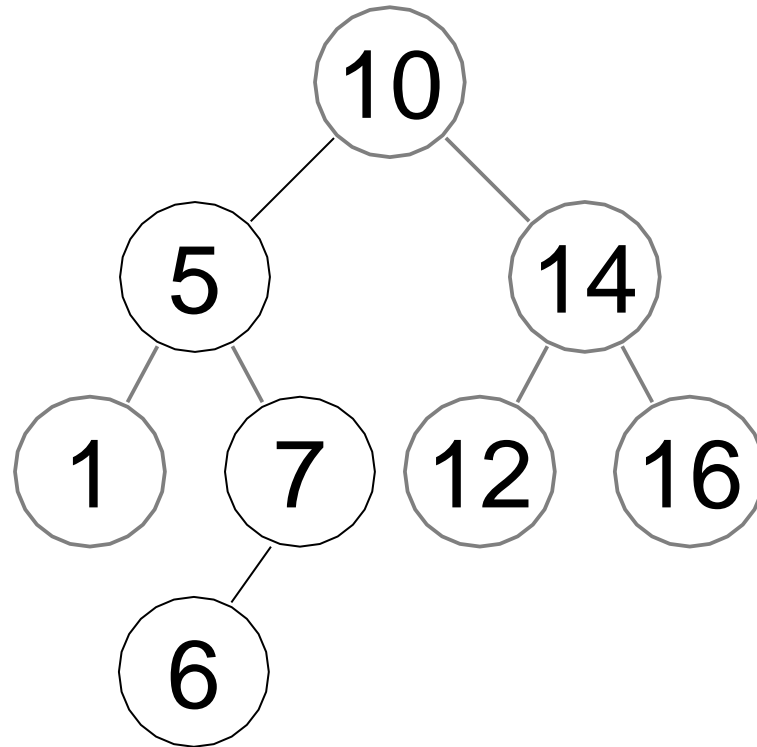
while N is not Null and $N.\text{Key} \leq y$

$L \leftarrow L + N$

$N \leftarrow \mathit{Successor}(N.\text{Key}, R, \text{Null})$

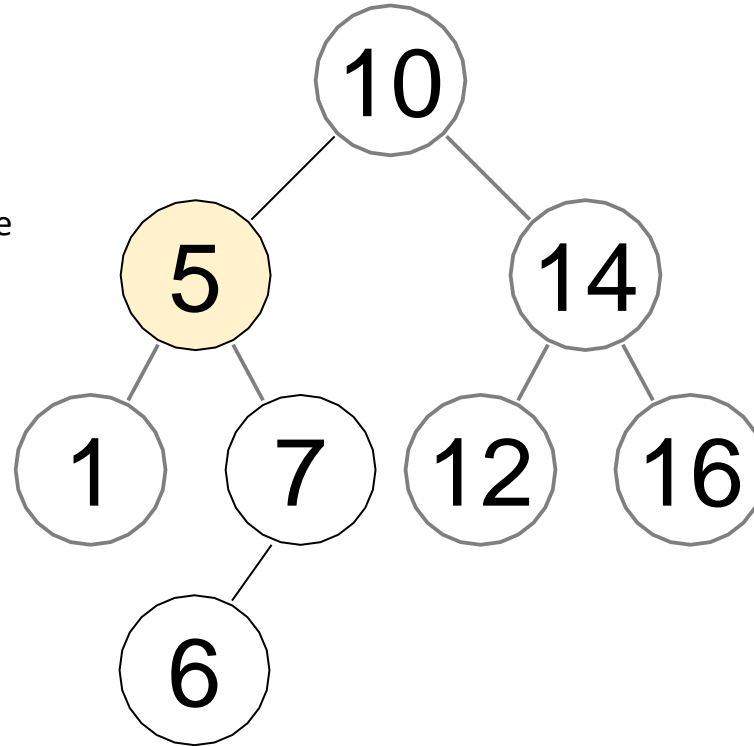
return L

Example: range search (5, 13)



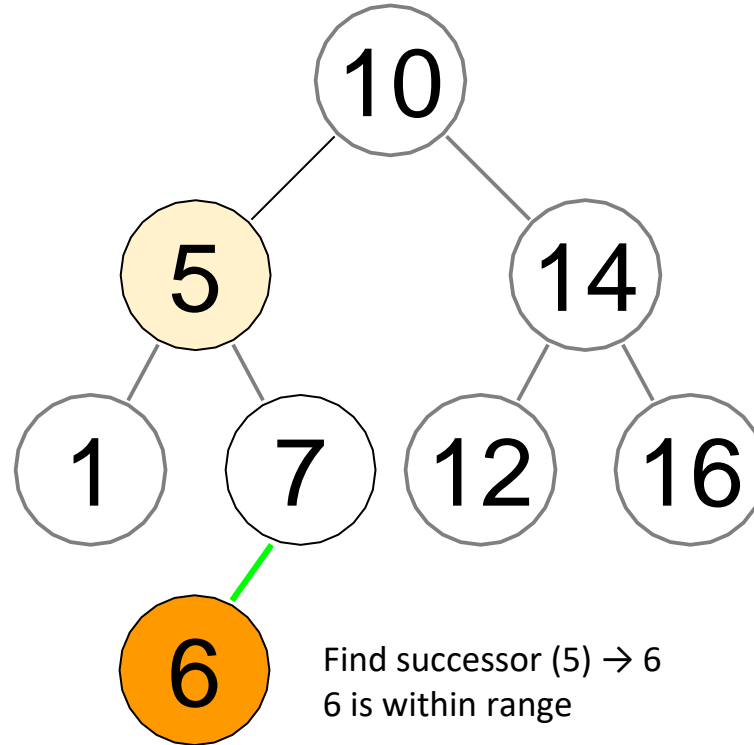
Example: range search (5, 13)

Find 5
5 is within range



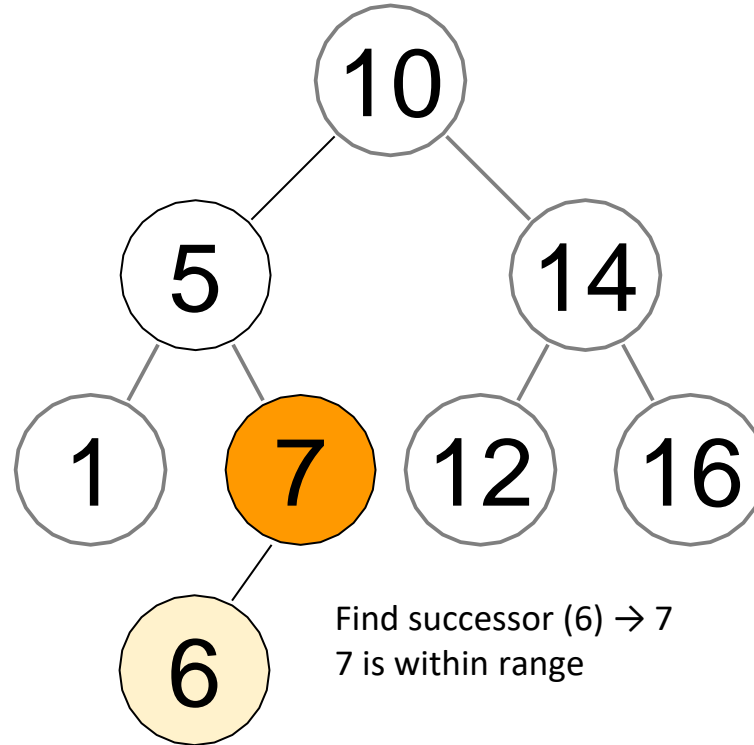
Result: 5

Example: range search (5, 13)



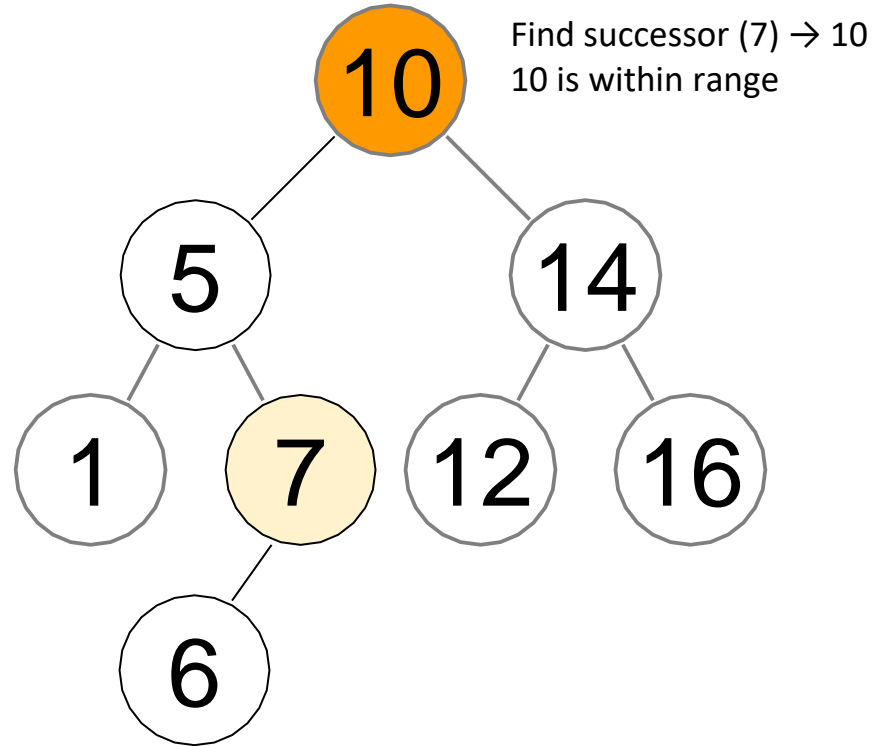
Result: 5, 6

Example: range search (5, 13)



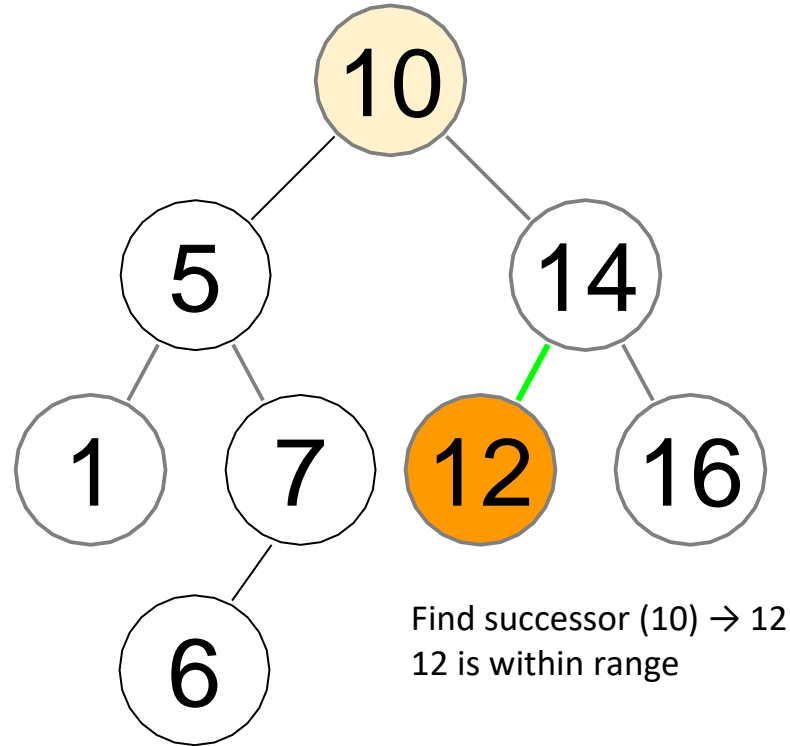
Result: 5, 6, 7

Example: range search (5, 13)



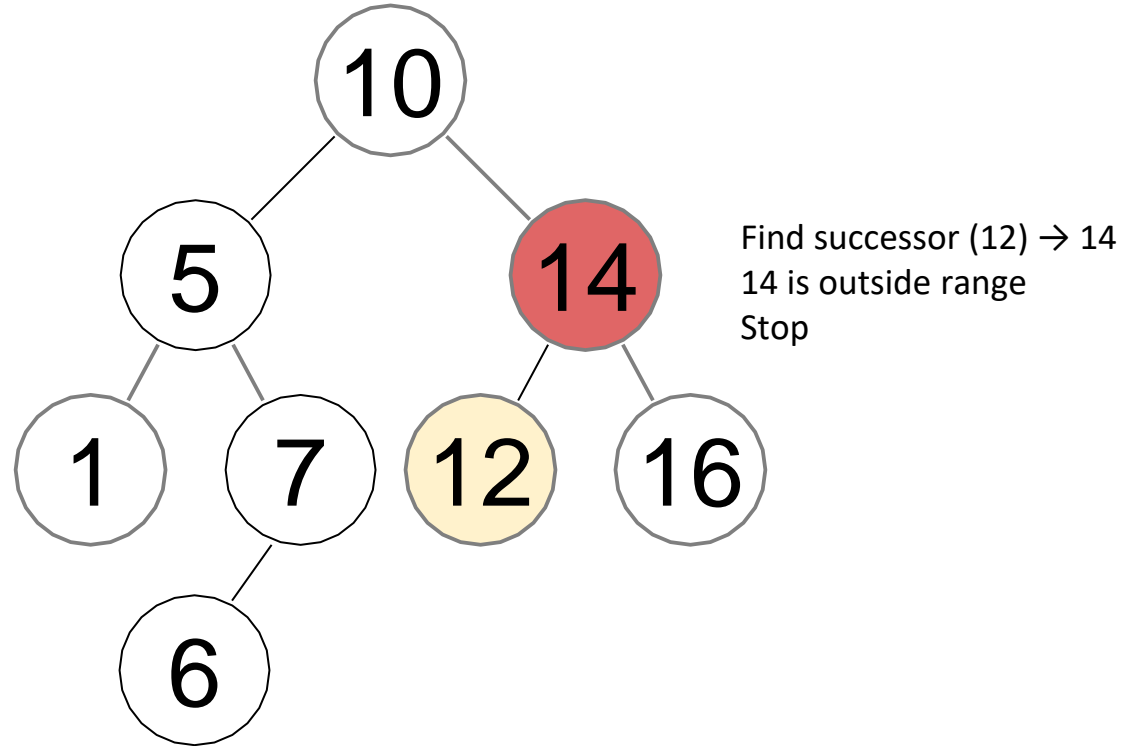
Result: 5, 6, 7, 10

Example: range search (5, 13)



Result: 5, 6, 7, 10, 12

Example: range search (5, 13)



Result: 5, 6, 7, 10, 12

BST: update operations

- ***Insert*** (k): creates a new node with key k and inserts it into the appropriate position of BST
- ***Delete*** (k): deletes the node with key k such that the BST property of the tree is preserved

We already have all the sub-operations to implement these

Operation *Insert*

Input: Key k

Output: Updated BST containing a new node N with key k

Algorithm *Find* (k, R)

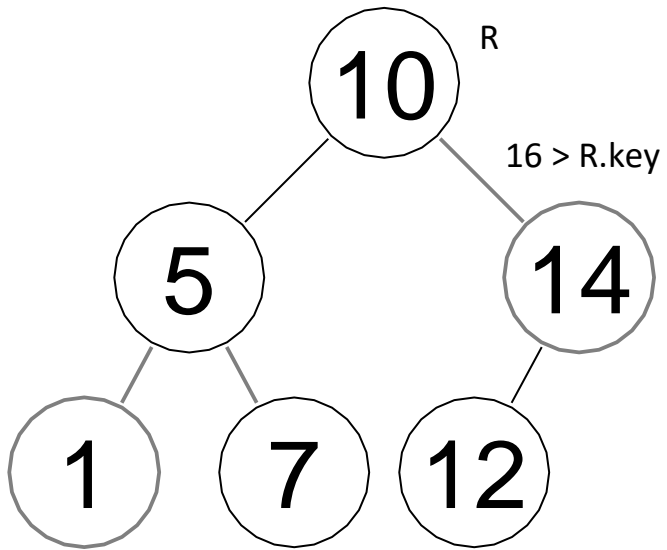
```
if  $R$  is Null or  $R.Key = k$ :  
    return  $R$   
if  $R.Key > k$ :  
    return Find( $k, R.Left$ )  
else if  $R.Key < k$ :  
    return Find( $k, R.Right$ )
```

We need to slightly modify *Find*

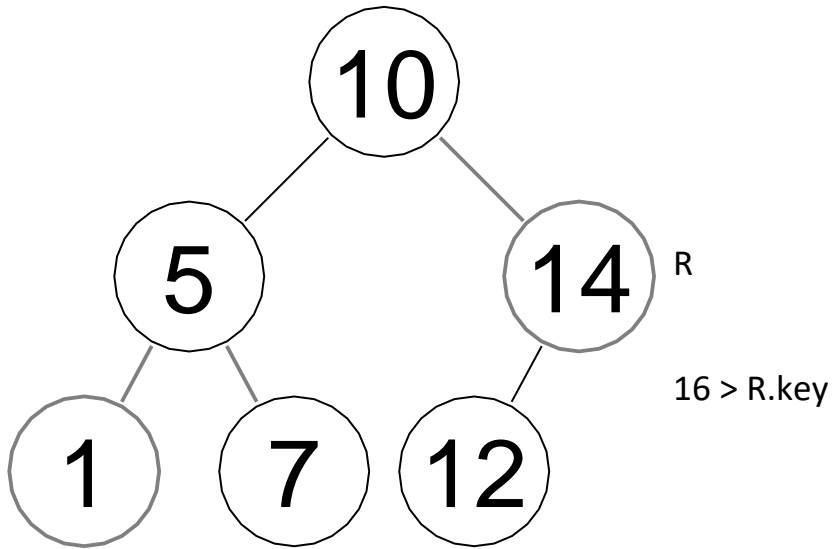
Algorithm *Insert* (k, R)

```
if  $R \neq \text{Null}$  and  $R.\text{Key} = k$ :  
    return ERROR  
if  $R$  is Null:  
    return new Node( $k$ )  
if  $k < R.\text{Key}$ :  
     $R.\text{left} = \text{Insert}(k, R.\text{left})$   
    return  $R$   
if  $k > R.\text{Key}$ :  
     $R.\text{right} = \text{Insert}(k, R.\text{right})$   
    return  $R$ 
```

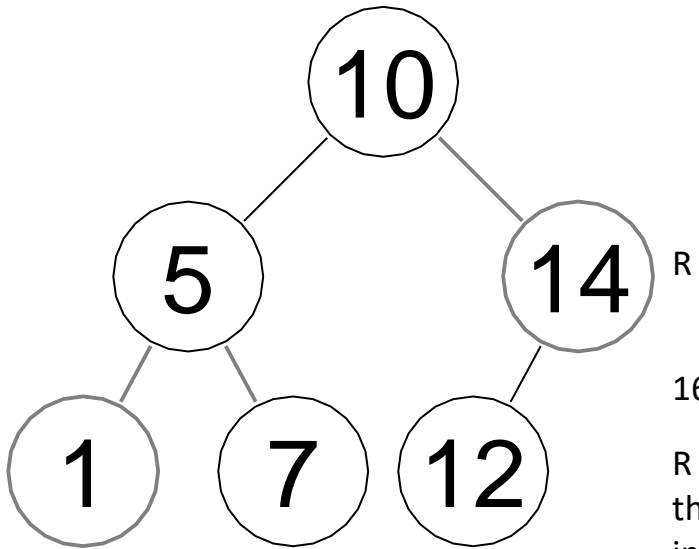

Example: insert (16, R)



Example: insert (16, R)



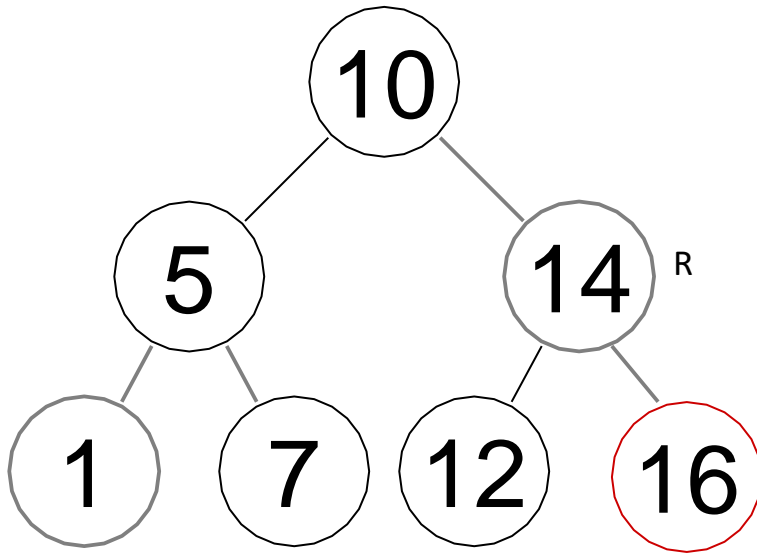
Example: insert (16, R)



16 > R.key

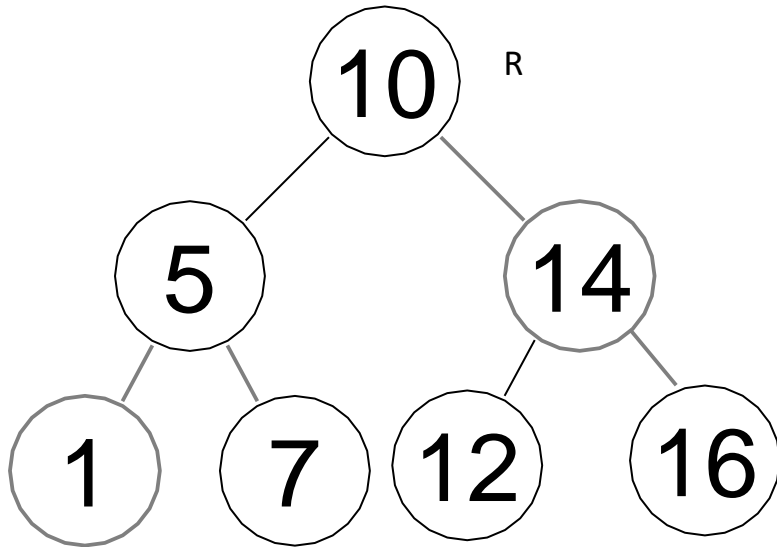
R has no right child -
this is the place to
insert new node

Example: insert (16, R)

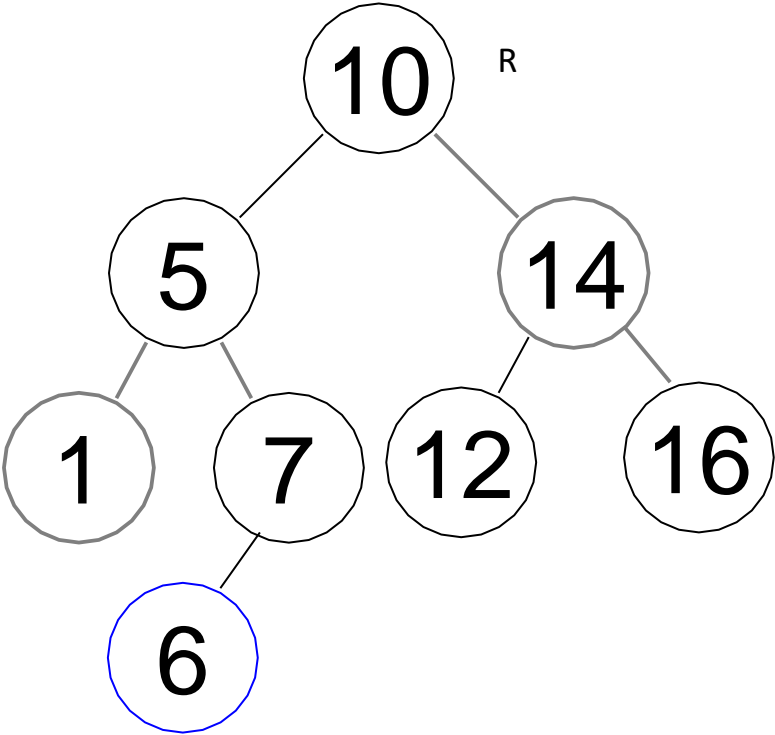


Update right child of
R and return updated
node 14

Example: insert (6, R)



Example: insert (6, R)



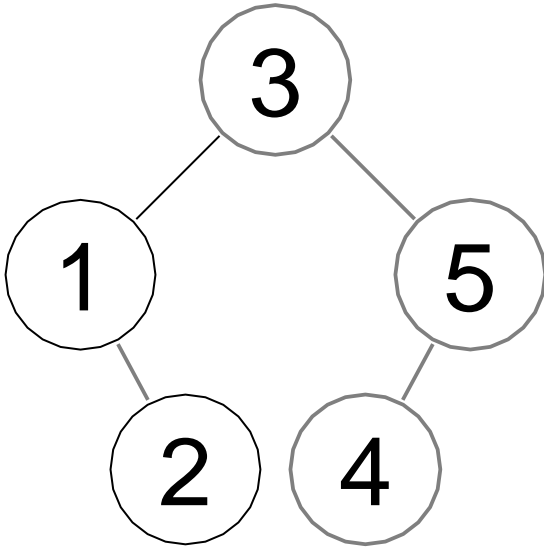
Operation Delete

Input: Key k

Output: BST without node N with key k

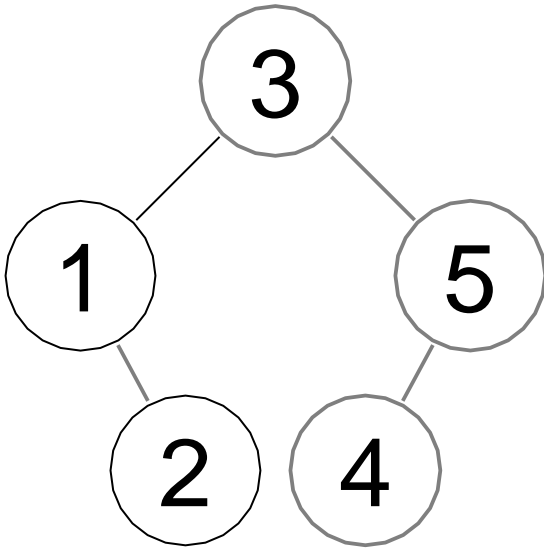
The most challenging algorithm in this module

Delete node N with key k



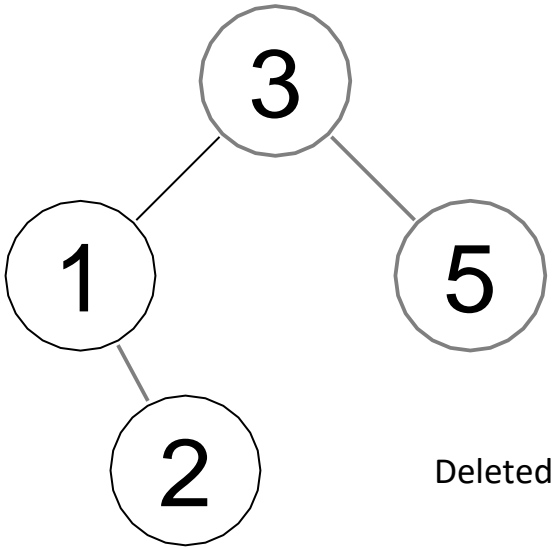
- First, find N
- Easy case (N has no children)
 - Just detach N from the tree

Example: *delete*(4)



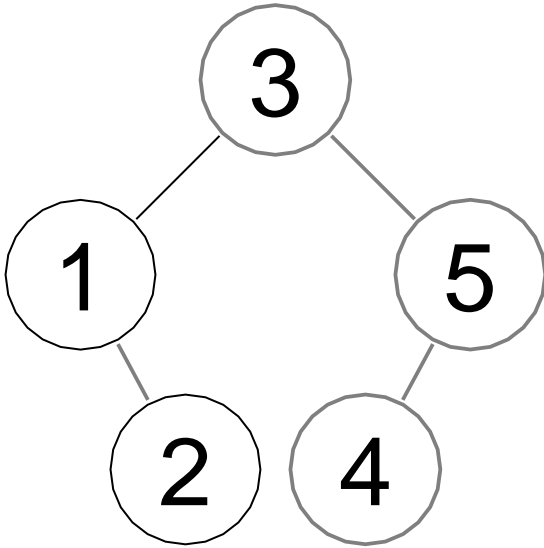
- First, find N
- Easy case (N has no children)
 - Just detach N from the tree

Example: *delete*(4)



- First, find N
- Easy case (N has no children)
 - Just detach N from the tree

Delete node N with key k

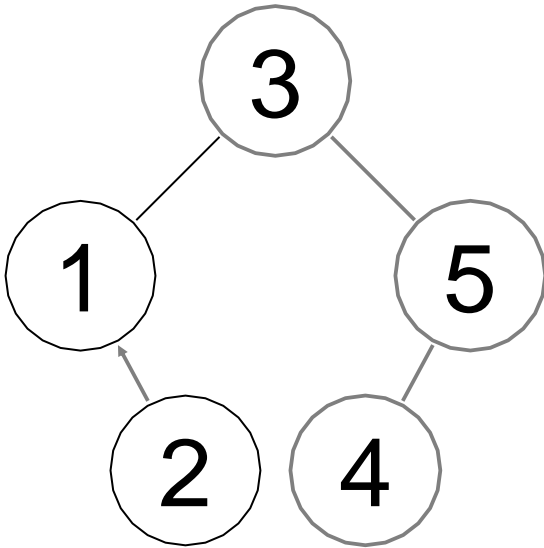


➤ Medium case (N has one child):

Just “splice out” node N

- Its unique child assumes the position previously occupied by N – gets ***promoted*** to its place

Example: *delete(1)*

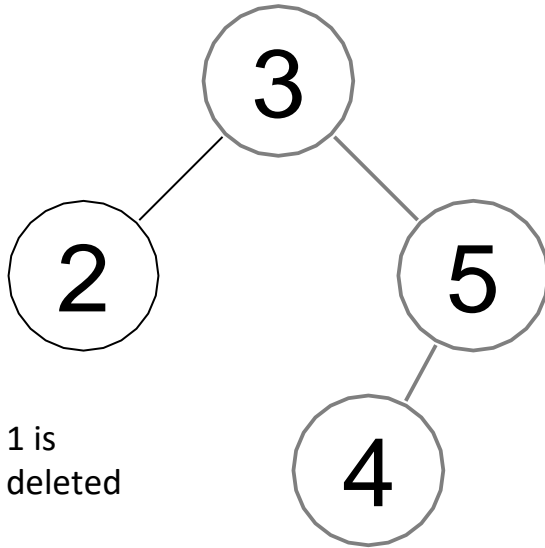


➤ Medium case (N has one child):

Just “splice out” node *N*

- Its unique child assumes the position previously occupied by *N* – gets ***promoted*** to its place

Example: *delete*(1)

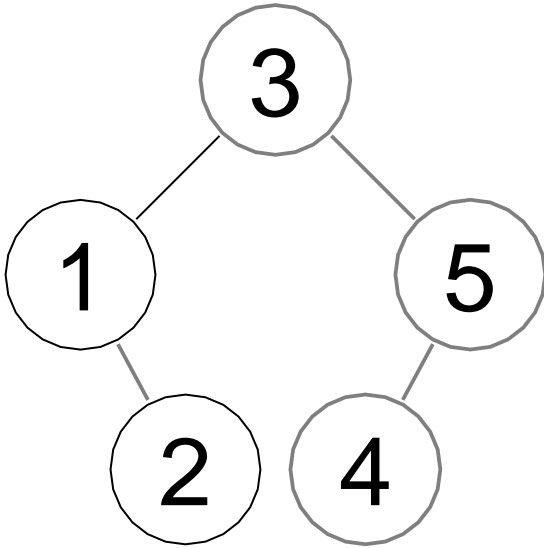


➤ Medium case (N has one child):

Just “splice out” node *N*

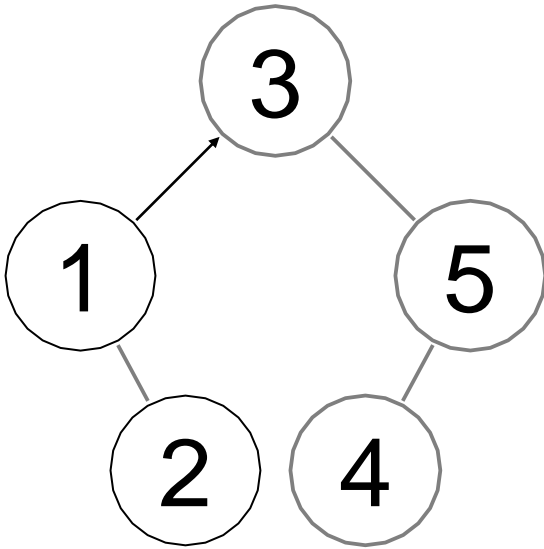
- Its unique child assumes the position previously occupied by *N* – gets ***promoted*** to its place

Delete node N with key k



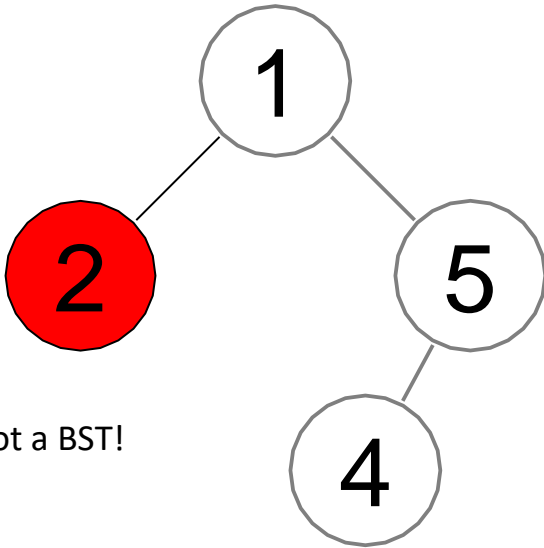
➤ Difficult case (N has 2 children):

Example: *delete*(3)



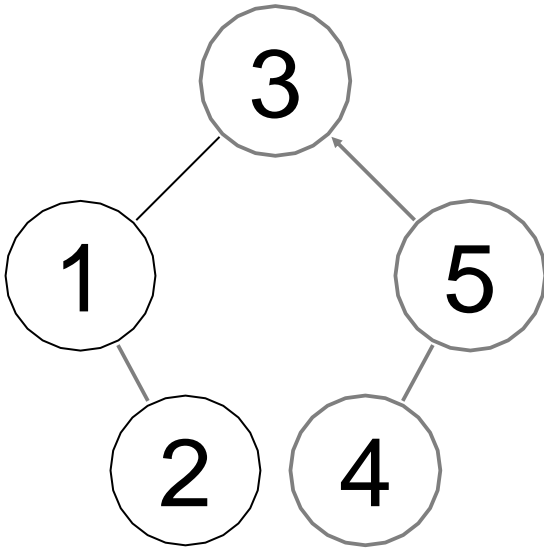
- Difficult case (N has 2 children):
 - Promote 1?

Example: *delete*(3)



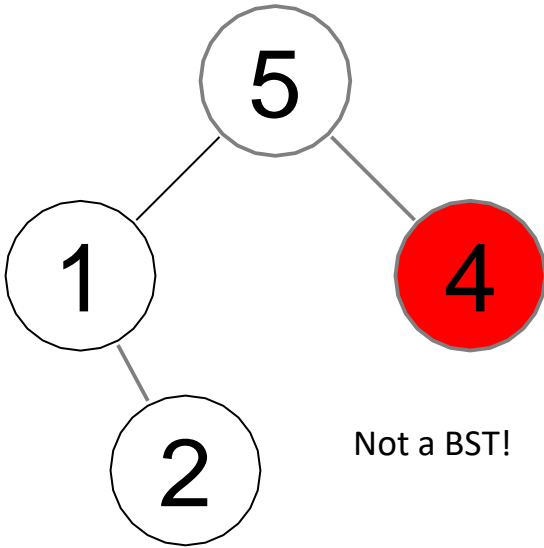
- Difficult case (N has 2 children):
 - Promote 1?

Example: *delete*(3)



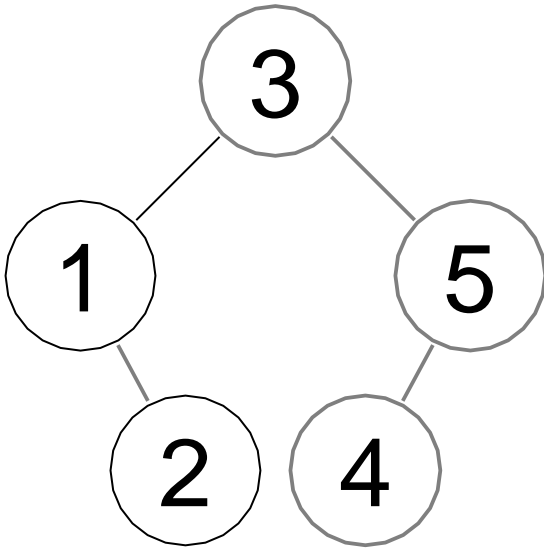
- Difficult case (N has 2 children):
 - Promote 5?

Example: *delete(3)*



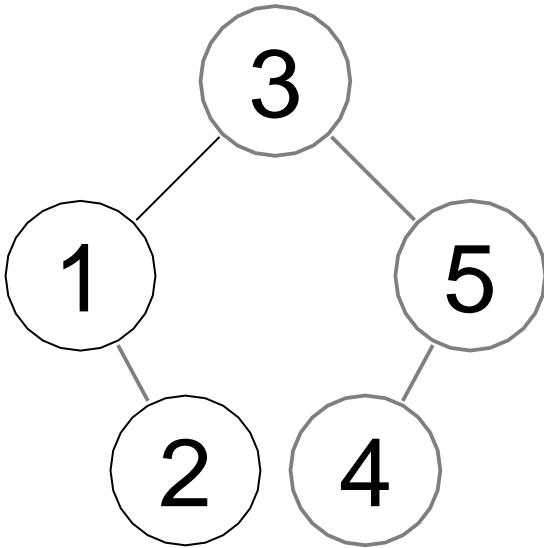
- Difficult case (N has 2 children):
 - Promote 5?

Delete node N with key k : difficult case



- Difficult case (N has 2 children):
 - We want to make as little changes to the tree structure as possible
 - Replace node N with its successor (with the next largest key)

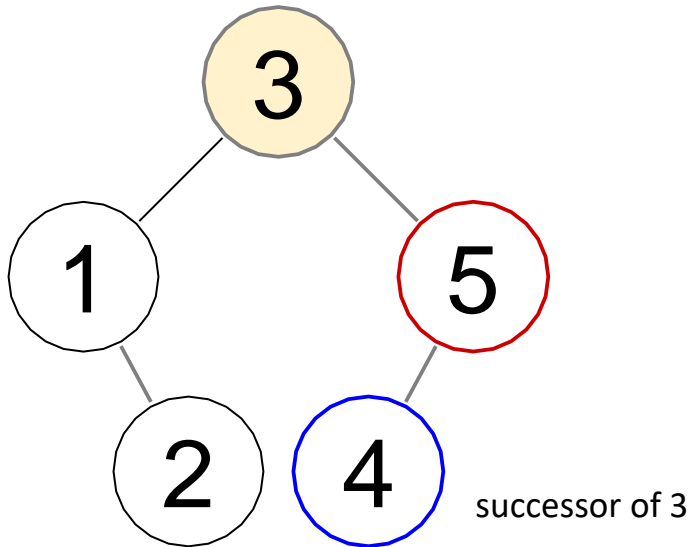
Delete node N with key k : difficult case



➤ Difficult case (N has 2 children):

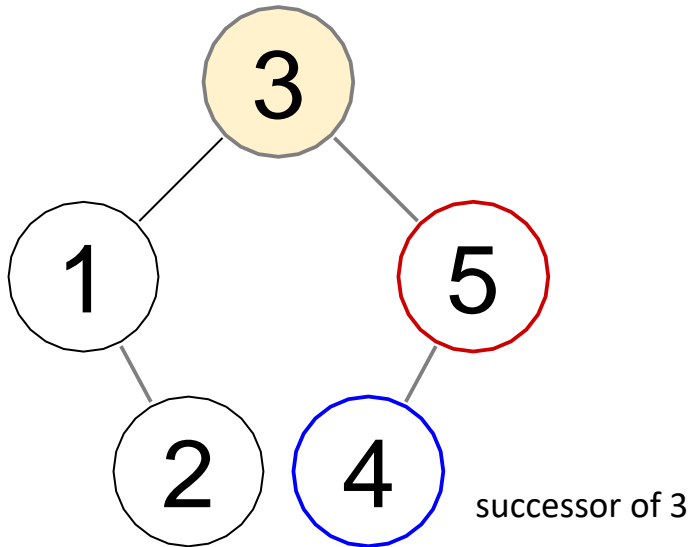
- Replace node N with its successor (with the next largest key)
- Luckily we know that N has the right child
- To find successor - look for a min in its right subtree

Example: *delete*(3)



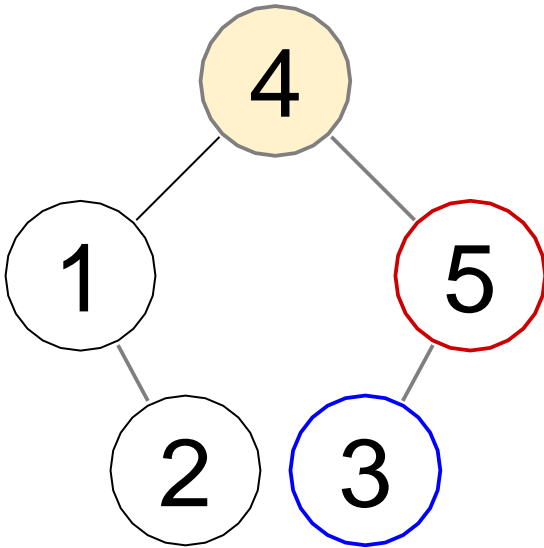
- Difficult case (N has 2 children):
 - Replace node N with its successor (with the next largest key)
 - To find successor - look for a min in its right subtree

Example: *delete*(3)



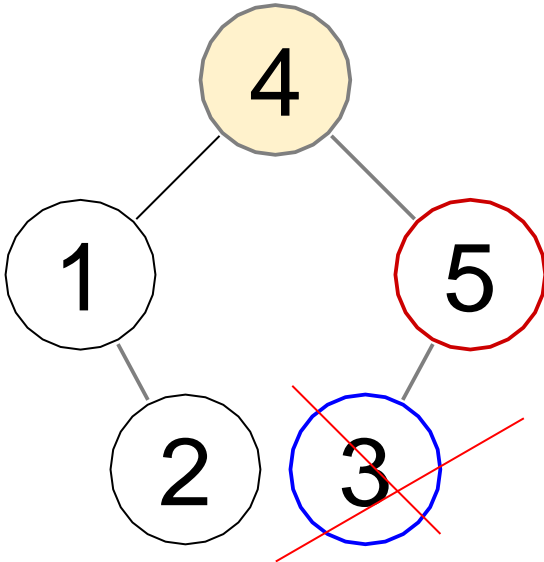
- Difficult case (N has 2 children):
 - Replace node N with its successor (with the next largest key)
 - To find successor - look for a min in its right subtree
 - Swap values in N and its successor

Example: *delete*(3)



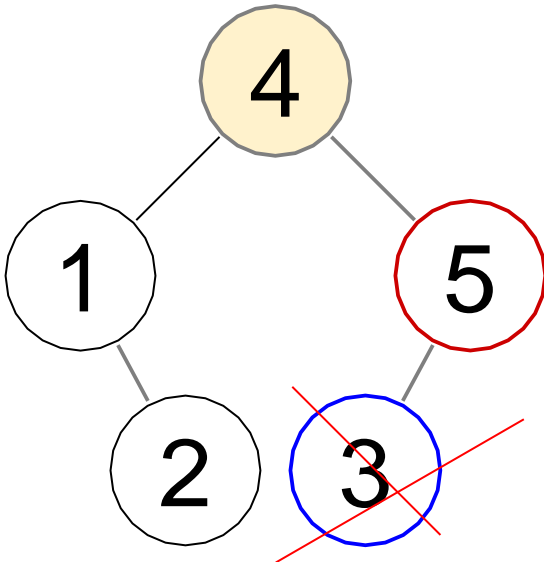
- Difficult case (N has 2 children):
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- Difficult case (N has 2 children):
 - Replace node N with its successor (with the next largest key)
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 - Swap values in N and its successor
 - Remove successor: this would be easy - why?

Example: *delete*(3)



➤ Difficult case (N has 2 children):

- Replace node N with its successor (with the next largest key)
- To find successor - look for a min in its right subtree
- Swap values in N and its successor
- Remove successor: this would be easy - why?

The successor **does not have a left child!**

(it was a min in the right subtree - which was the last possible left node)